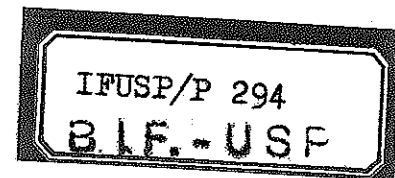


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EQUILIBRIUM CONDITIONS - A REMARK ON METASTABILITY

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ON THE GLOBAL CHARACTER OF SOME RESTRICTED EQUILIBRIUM CONDITIONS -  
A REMARK ON METASTABILITY

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ABSTRACT

For classical lattice systems with finite range interactions it is proven that if a state minimizes a free-energy functional at non-zero temperature with respect to variations of the state inside all regions of limited size (for instance, all regions with only one lattice site!) then it is a Gibbs state.

This result rules out the possibility of defining metastable states at  $T \neq 0$  as those which satisfy the thermodynamical stability conditions for regions with small volume to surface ratio, unlike the  $T=0$  case.

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I. INTRODUCTION

The equilibrium states of lattice systems with finite range interactions at non-zero temperature can be characterized by the D.L.R. condition [1]. This set of equations expresses the requirement that for every finite region the conditional probability of the internal configurations given the external configuration are Gibbsian.

The problem of characterization of metastable states of these systems in spite of several attempts remains largely open. In some approaches [2,3] states satisfying a restricted Gibbs condition were shown to display some desirable features [4] of metastable states. The restrictions imposed were in the configuration space of the system and enforced the state to be far from the equilibrium one. This paper originated from an attempt to provide a variational principle from which both the stable and metastable states would emerge as the only solutions. The motivation for this search is found in the analysis of the ground-state of the Ising model with an external field. There one easily sees that if we require that a state minimizes the energy with respect to variations of the state inside arbitrary regions of a "size" smaller than a certain critical value, then there are exactly two solutions: the true ground state and the "metastable" state (see Appendix). At non-zero temperature the natural generalization would consist in looking for states which minimize the free-energy with respect again to variations of the state inside arbitrary regions of not too large "size" ("size" stands for the ratio volume/surface). Our results are "no-go" theorems: the only solutions of this variational principle at  $T \neq 0$  is the true Gibbs state.

This paper is organized as follows. In section II we describe the systems under consideration and show that if a state

satisfies the D.L.R. equations for regions containing only one lattice site then it is a Gibbs state. In section III we show that the condition of Local Thermodynamical Stability (L.T.S.) [2b] restricted to a finite region implies the D.L.R. equation for that region. In the Appendix we present for completeness the  $T=0$  case which motivated the whole discussion.

We do not claim complete originality, as some of our results may be known in one form or another. For instance, a version of theorem 1, under slightly modified assumptions which are not sufficient for our purposes can be found in refs. [4,5]. However to the best of our knowledge the implications of these results to the theory of metastability have nowhere been discussed.

## II. RESTRICTED DLR CONDITION

All along this article we will consider a classical lattice system (spin system) with finite range interactions. At each site  $i$  of an infinite lattice  $\mathcal{S}$  (typically  $\mathbb{Z}^v$ ,  $v=1,2,3,\dots$ ) we have a finite state space  $\Gamma_i$ , which for simplicity we take to be independent of  $i$ ,  $\Gamma_i = \Gamma$ . A configuration  $x$  of this system is a function

$$x: \mathcal{S} \rightarrow \Gamma$$

$$i \rightarrow x(i) \in \Gamma$$

with  $x(i)$  denoting the configuration at the site  $i$ , i.e.  $x \in \Omega = \Gamma^{\mathcal{S}}$ . For a finite region  $\Lambda \subset \mathcal{S}$  we denote by  $x_\Lambda$  a configuration "inside  $\Lambda$ " i.e. a function  $x_\Lambda: \Lambda \rightarrow \Gamma$ , i.e.  $x_\Lambda \in \Omega_\Lambda = \Gamma^\Lambda$ . Given a configuration  $x \in \Omega$  we denote by  $x|_\Lambda$  its restriction to  $\Lambda$ . If  $\Lambda_1 \cap \Lambda_2 = \emptyset$  we denote by  $x_{\Lambda_1} x_{\Lambda_2}$  the joint configuration in  $\Omega_{\Lambda_1 \cup \Lambda_2}$ .

i.e.  $x_{\Lambda_1} x_{\Lambda_2}(i) = x_{\Lambda_1}(i)$  if  $i \in \Lambda_1$  and  $x_{\Lambda_1} x_{\Lambda_2}(i) = x_{\Lambda_2}(i)$  if  $i \in \Lambda_2$ . If  $\Lambda_2 \subset \Lambda_1$ , then  $x_{\Lambda_2}$  is the restriction of  $x_{\Lambda_1}$  to  $\Lambda_2$ .

A state of the system is a probability measure in the measure space  $(\Omega, \Sigma)$  where  $\Sigma$  is the  $\sigma$ -field generated by the cylinder sets. Given a state  $\mu$  we denote by  $p(x_\Lambda)$  the probability that the configuration inside  $\Lambda$  is  $x_\Lambda$  i.e.  $p(x_\Lambda) = \mu(\{x: x|_\Lambda = x_\Lambda\})$ .

The interaction is given by a collection  $(\phi_\Lambda, \Lambda \in \mathcal{S}, \Lambda$  finite) of functions  $\phi_\Lambda: \Omega_\Lambda \rightarrow \mathbb{R}$ . The interaction is said to have range  $R$  if  $\phi_\Lambda = 0$  when diameter of  $\Lambda > R$ . Of course  $\phi_\Lambda$  can be considered as function on  $\Omega$  via  $\phi_\Lambda(x) = \phi_\Lambda(x|_\Lambda)$ . We denote by  $H_\Lambda$  the energy in the interior of  $\Lambda$ , i.e.

$$H_\Lambda = \sum_{x \subset \Lambda} \phi_x$$

and by  $V_\Lambda$  the interaction between sites in  $\Lambda$  and in  $\Lambda^c$ , i.e.

$$V_\Lambda = \sum_{\substack{x \cap \Lambda \neq \emptyset \\ x \cap \Lambda^c \neq \emptyset}} \phi_x$$

For each finite  $\Lambda$  we define

$$\Lambda_\phi = \{i \in \mathcal{S} : \phi_x \neq 0 \text{ for some } x \ni i, x \cap \Lambda \neq \emptyset\}$$

$$\Delta\Lambda = \Lambda_\phi \setminus \Lambda.$$

With the above notation a state is said to verify the D.L.R. equation at inverse temperature  $\beta < \infty$  if

$$p(x_\Lambda y_{\Delta\Lambda}) = T(x_\Lambda | y_{\Delta\Lambda}) p(y_{\Delta\Lambda})$$

for each finite  $\Lambda' \supset \Delta\Lambda$ ,  $\Lambda' \cap \Lambda = \emptyset$ , where

$$T(x_\Lambda | y_{\Delta\Lambda}) = \frac{\exp\{-\beta(H_\Lambda + V_\Lambda)(x_\Lambda | y_{\Delta\Lambda})\}}{\sum_{z_\Lambda} \exp\{-\beta(H_\Lambda + V_\Lambda)(z_\Lambda | y_{\Delta\Lambda})\}}$$

A state is said to be a (global) D.L.R. state if it verifies the D.L.R. equation for each finite region  $\Lambda \subset \mathbb{S}$  [1].

**Definition:** A state is a restricted D.L.R. state if it verifies the D.L.R. equations for each region  $\Lambda$  of one single site, i.e.  $\Lambda = \{i\}$  for some  $i \in \mathbb{S}$ .

**Theorem 1:** For classical lattice systems with finite range interactions a restricted D.L.R. state is a (global) D.L.R. state.

For the proof of the theorem we need the following lemma.

**Lemma:** For a restricted D.L.R. state of a classical lattice system at finite inverse temperature  $p(x_\Lambda) \neq 0 \forall x_\Lambda \in \Gamma^\Lambda$  for all finite  $\Lambda$ .

**Proof of the lemma:** We will proceed by induction on the size of the region. Let  $|\Lambda|=1$ , then from the restricted D.L.R. condition.

$$p(x_\Lambda) = \sum_{y_{\Delta\Lambda}} p(x_\Lambda y_{\Delta\Lambda}) = \sum_{y_{\Delta\Lambda}} p(y_{\Delta\Lambda}) T(x_\Lambda | y_{\Delta\Lambda}) \quad (II.1)$$

since  $T(x_\Lambda | y_{\Delta\Lambda}) > 0$  and  $\sum_{y_{\Delta\Lambda}} p(y_{\Delta\Lambda}) = 1, p(y_{\Delta\Lambda}) \geq 0$  (II.1) implies  $p(x_\Lambda) > 0$ .

Let us assume that  $p(x_\Lambda) > 0$  for all  $\Lambda$  such that  $|\Lambda|=N$ ,  $\forall x_\Lambda \in \Gamma^\Lambda$ . Let  $\Lambda' = \Lambda \cup i, i \notin \Lambda, |i|=1, |\Lambda|=N$  and

$$\tilde{i} = \Delta i / \Lambda$$

If  $\tilde{i} = \emptyset$  then  $\Delta i \subset \Lambda$  and the restricted D.L.R. equation for  $i$  implies

$$p(x_{\Lambda'}) = p(x_i | x_\Lambda) = T(x_i | x_{\Delta i}) p(x_\Lambda)$$

and since by the induction assumption  $p(x_\Lambda) > 0$ , we have  $p(x_{\Lambda'}) > 0$  in this case.

If  $\tilde{i} \neq \emptyset, \Delta i \subset \tilde{i} \cup \Lambda$  and

$$p(x_{\Lambda'}, y_{\tilde{i}}^-) = p(x_i | x_\Lambda y_{\tilde{i}}^-) = T(x_i | z_{\Delta i}) p(x_\Lambda y_{\tilde{i}}^-) \quad (II.2)$$

where  $z_{\Delta i}$  is the configuration whose restrictions are

$$z_{\Lambda \cap \Delta i} = x_{\Lambda \cap \Delta i} \quad z_{\tilde{i}}^- = y_{\tilde{i}}^-$$

$$\text{Now } \sum_{y_{\tilde{i}}^-} p(x_\Lambda y_{\tilde{i}}^-) = p(x_\Lambda) > 0$$

therefore  $p(x_\Lambda y_{\tilde{i}}^-) > 0$  for some  $y_{\tilde{i}}^-$ . From (II.2) we conclude that some  $p(x_{\Lambda'}, y_{\tilde{i}}^-) > 0$  and since  $p(x_{\Lambda'}) = \sum_{y_{\tilde{i}}^-} p(x_{\Lambda'}, y_{\tilde{i}}^-)$  we obtain  $p(x_{\Lambda'}) > 0$ .

**Remark:** Notice that the lemma is false for the ground state ( $\beta = \infty$ ).

**Proof of Theorem 1:** Given a finite  $\Lambda \subset \mathbb{S}$  and a finite  $\Lambda' \supset \Delta\Lambda$ ,  $\Lambda' \cap \Lambda = \emptyset$ , let  $i \subset \Lambda, |i|=1, S_i = (\Lambda \cup \Lambda') / i$ . Clearly  $S_i \supset \Delta i$ . Then the restricted D.L.R. condition implies

$$p(x_i | y_{S_i}) = p(y_{S_i}) T(x_i | y_{\Delta i})$$

Using the lemma

$$\frac{p(x_i y_{S_i})}{p(z_i y_{S_i})} = \frac{T(x_i | y_{\Delta i})}{T(z_i | y_{\Delta i})} = \frac{\exp\{-\beta [H_i(x_i) + V_i(x_i y_{\Delta i})]\}}{\exp\{-\beta [H_i(z_i) + V_i(z_i y_{\Delta i})]\}} =$$

$$= \frac{\exp\{-\beta H_{\Lambda \cup \Lambda'}(x_i y_{S_i})\}}{\exp\{-\beta H_{\Lambda \cup \Lambda'}(z_i y_{S_i})\}}$$

This means that for any two configurations  $x_{\Lambda_0}, z_{\Lambda_0}$  of  $\Lambda_0 = \Lambda \cup \Lambda'$  which differ just at a single site  $i \in \Lambda$

$$\frac{p(x_{\Lambda_0})}{p(z_{\Lambda_0})} = \frac{\exp\{-\beta H_{\Lambda_0}(x_{\Lambda_0})\}}{\exp\{-\beta H_{\Lambda_0}(z_{\Lambda_0})\}}$$

Now given any pair of configurations  $x_{\Lambda_0}, z_{\Lambda_0}$  inside  $\Lambda_0$  that differ only inside  $\Lambda$  we can construct a chain  $y_{\Lambda_0}^{(1)}, \dots, y_{\Lambda_0}^{(N)}$  of configurations in  $\Lambda_0$ , such that  $y_{\Lambda_0}^{(1)} = x_{\Lambda_0}, y_{\Lambda_0}^{(N)} = z_{\Lambda_0}$  with  $y_{\Lambda_0}^{(k)}$  differing from  $y_{\Lambda_0}^{(k+1)}$ ,  $k=1, \dots, N-1$  only at one site inside  $\Lambda$ . Then

$$\frac{p(x_{\Lambda_0})}{p(z_{\Lambda_0})} = \frac{p(y_{\Lambda_0}^{(1)})}{p(y_{\Lambda_0}^{(2)})} \dots \frac{p(y_{\Lambda_0}^{(N-1)})}{p(y_{\Lambda_0}^{(N)})} = \frac{\exp\{-\beta H_{\Lambda_0}(x_{\Lambda_0})\}}{\exp\{-\beta H_{\Lambda_0}(z_{\Lambda_0})\}} \quad (II.3)$$

The above relation implies de D.L.R. equation for the region

In fact (II.3) may be rewritten in the form

$$\frac{p(x_{\Lambda} y_{\Lambda'})}{p(z_{\Lambda} y_{\Lambda'})} = \frac{\exp\{-\beta H_{\Lambda_0}(x_{\Lambda} y_{\Lambda'})\}}{\exp\{-\beta H_{\Lambda_0}(z_{\Lambda} y_{\Lambda'})\}} = \frac{\exp\{-\beta H_{\Lambda \phi}(x_{\Lambda} y_{\Delta \Lambda'})\}}{\exp\{-\beta H_{\Lambda \phi}(z_{\Lambda} y_{\Delta \Lambda'})\}}$$

and since  $\sum_{z_{\Lambda}} p(z_{\Lambda} y_{\Lambda'}) = p(y_{\Lambda'})$  we get  $p(x_{\Lambda} y_{\Lambda'}) = p(y_{\Lambda'}) T(x_{\Lambda} | y_{\Lambda'})$ .

### III. RESTRICTED LOCAL THERMODYNAMICAL STABILITY

Following Sewell [2b] we define the free energy content of a region  $\Lambda$  in the state  $\mu$  by

$$F_{\Lambda}(\mu) = \int d_{\mu_{\Lambda^c}}(y_{\Lambda^c}) \sum_{x_{\Lambda}} \{ \tilde{\mu}(x_{\Lambda} | y_{\Lambda^c}) (H_{\Lambda} + V_{\Lambda})(x_{\Lambda} y_{\Delta \Lambda}) + kT \tilde{\mu}(x_{\Lambda} | y_{\Lambda^c}) \ln \tilde{\mu}(x_{\Lambda} | y_{\Lambda^c}) \}$$

where  $\mu_{\Lambda^c}$  is the restriction of the state to the complement  $\Lambda^c$  of  $\Lambda$  and  $\tilde{\mu}(x_{\Lambda} | y_{\Lambda^c})$  is the conditional probability of  $x_{\Lambda}$  given  $y_{\Lambda^c}$ .

A state  $\mu$  is said to be (globally) L.T.S. if for each finite  $\Lambda$

$$F_{\Lambda}(\mu') \geq F_{\Lambda}(\mu)$$

for all  $\mu'$  such that  $\mu'_{\Lambda^c} = \mu_{\Lambda^c}$ . In other words the state is L.T.S. if the free energy content of the state in the region  $\Lambda$  is minimum with respect to variations of the state inside  $\Lambda$ , for all finite  $\Lambda$ . For finite range interactions L.T.S. implies D.L.R. condition [2b]. The theorem below implies even more.

**Theorem 2:** Let  $\Lambda$  be a finite subset of  $\mathcal{S}$  and  $\mu$  be a state of a system with finite range interaction for which  $F_{\Lambda}(\mu') \geq F_{\Lambda}(\mu)$  for all  $\mu'$  such that  $\mu'_{\Lambda^c} = \mu_{\Lambda^c}$ . Then the state  $\mu$  verifies the D.L.R. equation for the region  $\Lambda$ .

**Proof:** For a given  $y_{\Lambda^c}$  let  $f_{y_{\Lambda^c}}$  denote the free-energy functional

$$f_{y_{\Lambda^c}}(\mu(x_{\Lambda})) = \sum_{x_{\Lambda}} \{ \mu(x_{\Lambda}) (H_{\Lambda} + V_{\Lambda})(x_{\Lambda} y_{\Delta \Lambda}) + kT \mu(x_{\Lambda}) \ln \mu(x_{\Lambda}) \}$$

It is well known that the unique minimum of this functional is attained at

$$\mu_{Y_{\Lambda^c}}(x_{\Lambda}) = T(x_{\Lambda} | Y_{\Delta\Lambda})$$

Therefore given a state  $\mu$ , if it minimizes  $F_{\Lambda}$  against variations inside  $\Lambda$

$\tilde{\mu}(x_{\Lambda} | Y_{\Lambda^c}) = T(x_{\Lambda} | Y_{\Delta\Lambda})$  for almost all  $Y_{\Lambda^c}$ . If  $\Delta\Lambda \subset \Lambda'$  and  $p(Y_{\Lambda'}) \neq 0$  then

$$\tilde{\mu}(x_{\Lambda} | Y_{\Lambda'}) = \frac{\int_{z|_{\Lambda'}=Y_{\Lambda'}} d\mu_{\Lambda^c}(z_{\Lambda^c}) \tilde{\mu}(x_{\Lambda} | z_{\Lambda^c})}{\int_{z|_{\Lambda'}=Y_{\Lambda'}} d\mu_{\Lambda^c}(z_{\Lambda^c})} = T(x_{\Lambda} | Y_{\Delta\Lambda})$$

and  $p(x_{\Lambda} Y_{\Lambda'}) = T(x_{\Lambda} | Y_{\Delta\Lambda}) p(Y_{\Lambda'})$  (III.1)

If  $p(Y_{\Lambda'}) = 0$ , then  $p(x_{\Lambda} Y_{\Lambda'}) = 0$  and (III.1) which is the D.L.R. equation for  $\Lambda$  is true too.

APPENDIX - A RESTRICTED VARIATIONAL PRINCIPLE FOR METASTABLE STATES

AT  $T=0$ .

Let for simplicity consider an Ising Model in  $Z^{\nu}$  at  $T=0$  with nearest neighbor interaction, with a hamiltonian given formally by

$$H = -J \sum_{\langle ij \rangle} \sigma_i \sigma_j + h \sum_{i \in Z^{\nu}} \sigma_i$$

where the  $\sum$  is the sum over all pairs of nearest neighbor sites,  $\langle ij \rangle$

with  $J>0, h>0$ . The ground state of the system is a measure  $\mu_-$  concentrated in the configuration  $x_-$  with all spins down, i.e.  $x_-(i) = -1, \forall i \in Z^{\nu}$ :

$$\mu_-(E) = 1, \quad x_- \in E \in \Sigma$$

$$\mu_-(E) = 0, \quad x_- \notin E \in \Sigma.$$

If  $0 < h < 2\nu J$  then the state  $\mu_+(E) = \mu_-(-E)$  is the "metastable state" and verifies the following variational principle: for all regions  $\Lambda$  such that  $h|\Lambda| \leq 2\nu J|\partial\Lambda|$  where  $|\Lambda|$  and  $|\partial\Lambda|$  are the volume and surface of  $\Lambda$  respectively

$$F_{\Lambda}(\mu') \geq F_{\Lambda}(\mu_+)$$

for all  $\mu'$  s.t.  $\mu'_{\Lambda^c} = \mu_{+\Lambda^c}$  as one trivially verifies. Here  $F_{\Lambda}(\mu)$  is as defined in section III for  $T=0$ .

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